



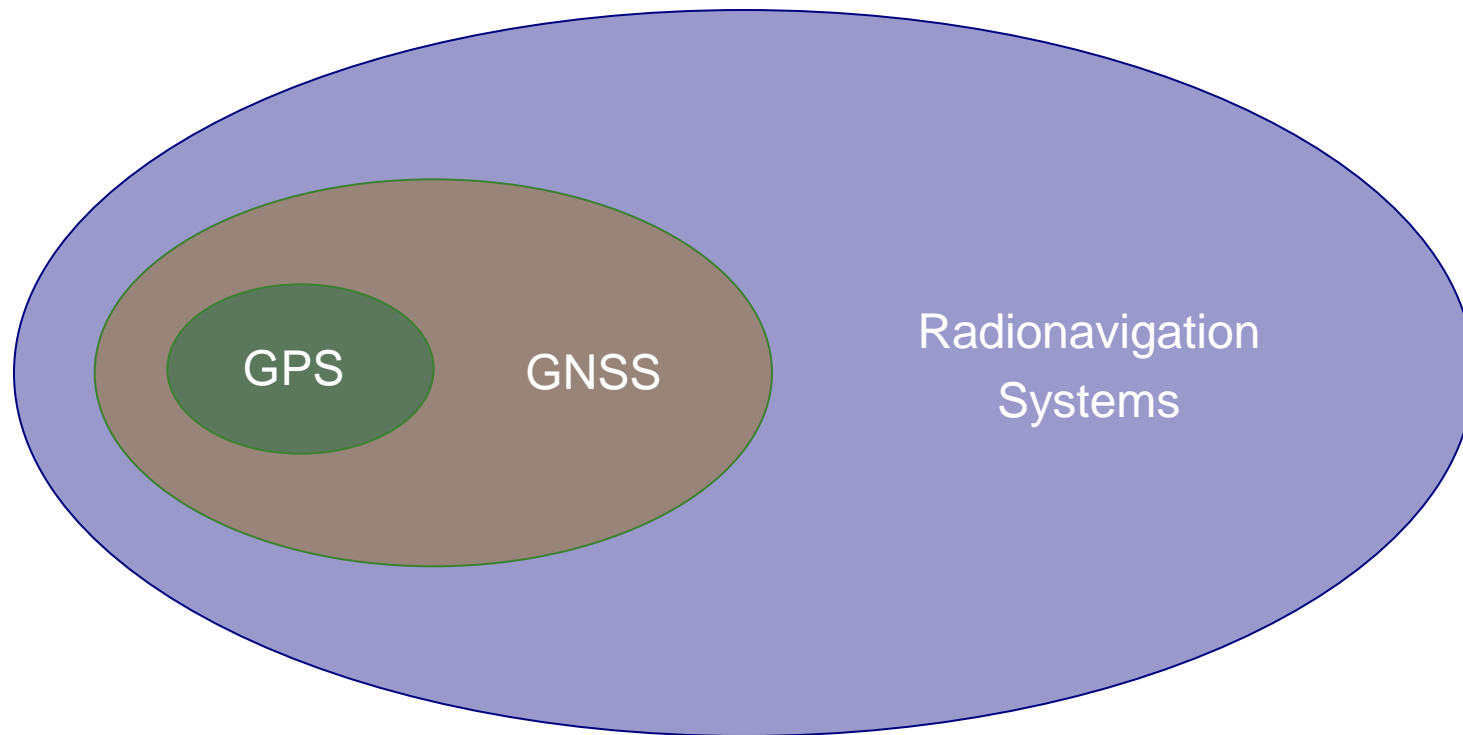
THE UNIVERSITY OF TEXAS AT AUSTIN  
**RADIONAVIGATION LABORATORY**



# Frontiers in Radionavigation

Dr. Todd E. Humphreys

# Radionavigation



# GPS: The Big Issues

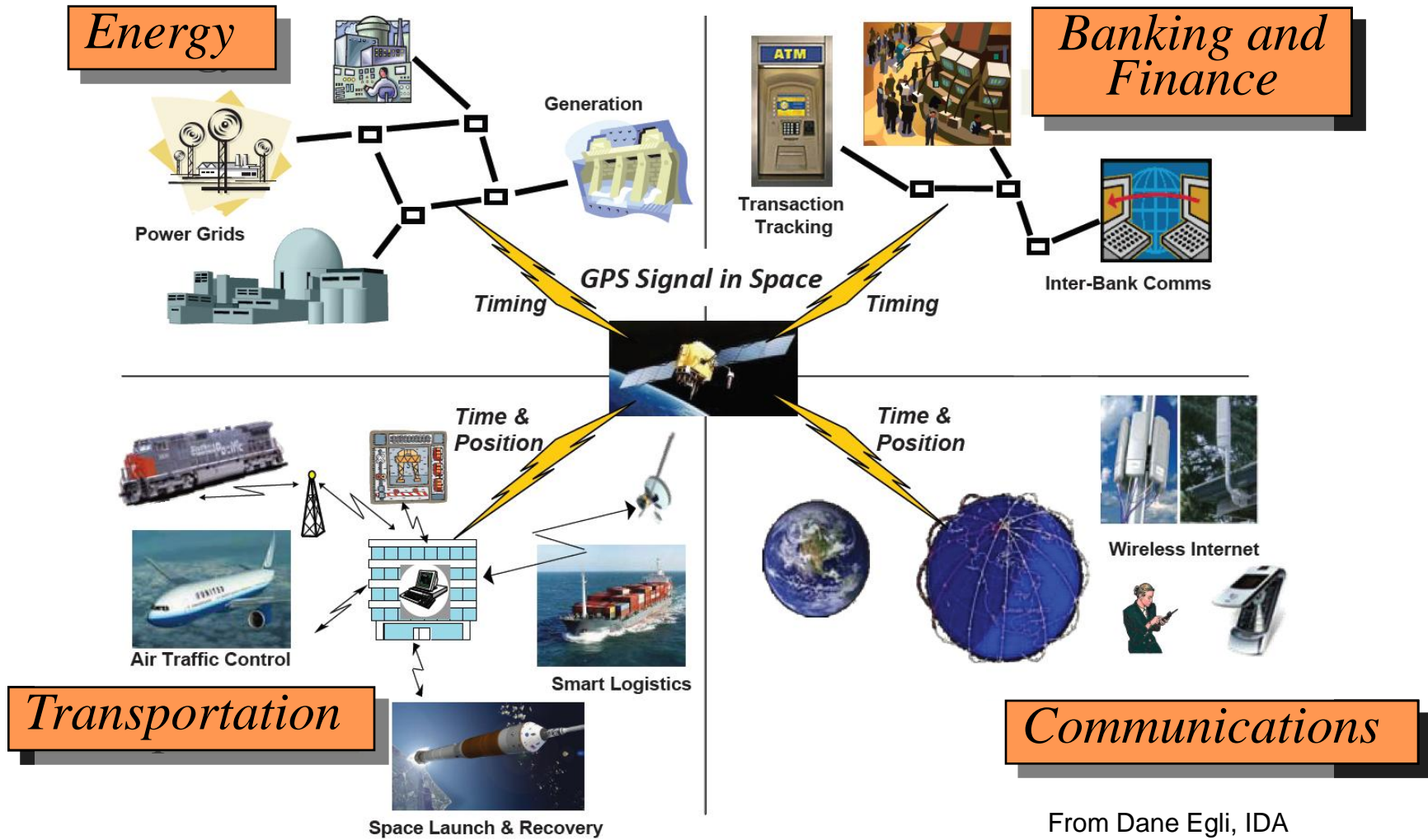
## ■ **Weak GPS Signals**

- Like a 30-Watt lightbulb held 4000 km away
- GPS does not penetrate well indoors
- GPS is easy target for jamming
- GPS is vulnerable to natural interference (e.g., solar radio bursts and ionospheric scintillation)

## ■ **Unauthenticated Civil GPS Signals**

- Civil GPS broadcast “in the clear”
- Makes civil GPS vulnerable to spoofing

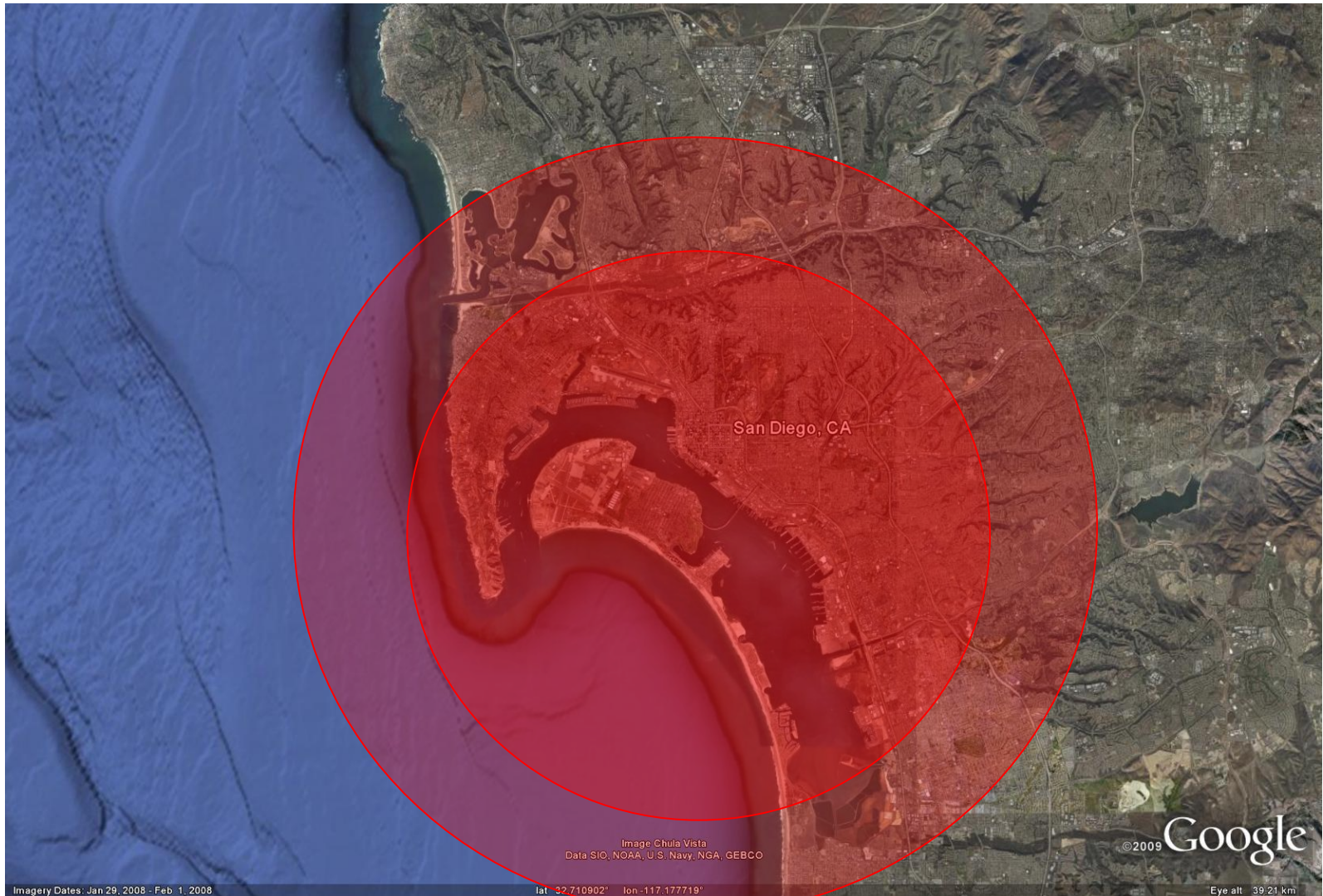
# GPS: Dependency Begets Vulnerability



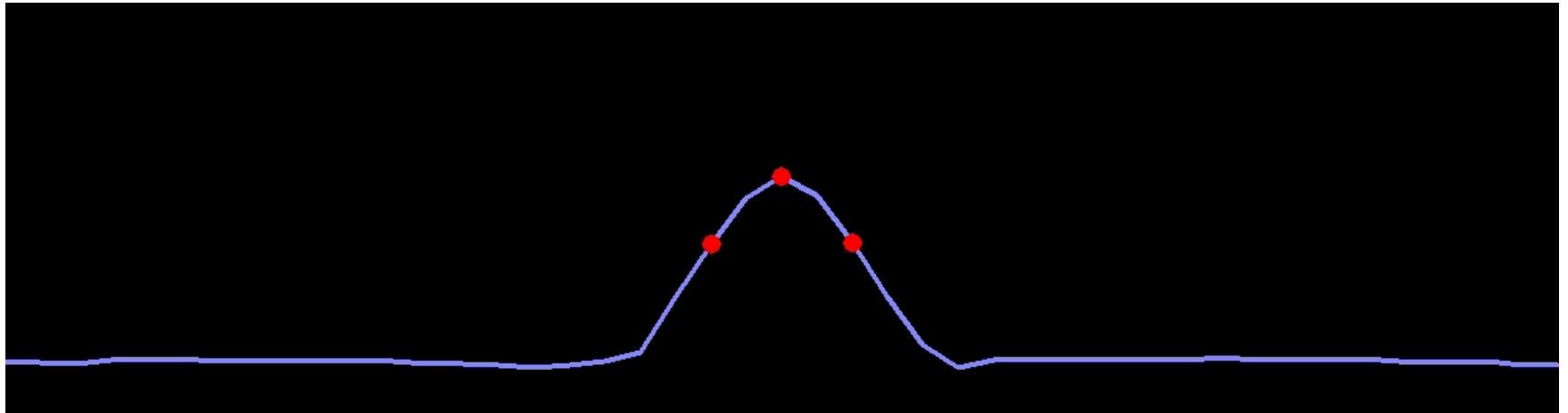
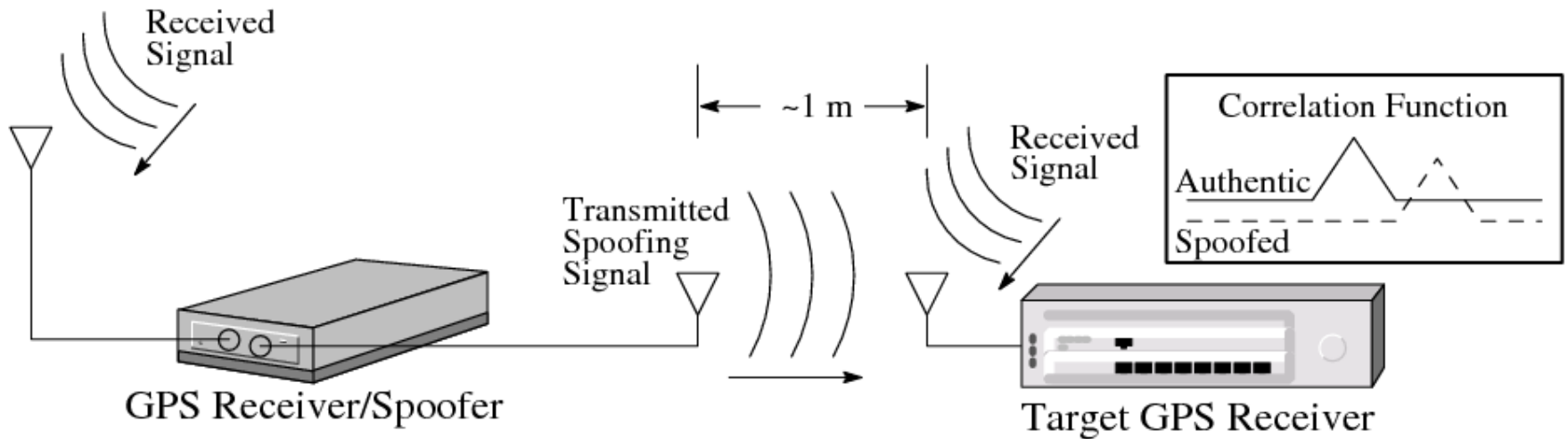
From Dane Egli, IDA



# Civil GPS Jamming Event



# Civil GPS Spoofing

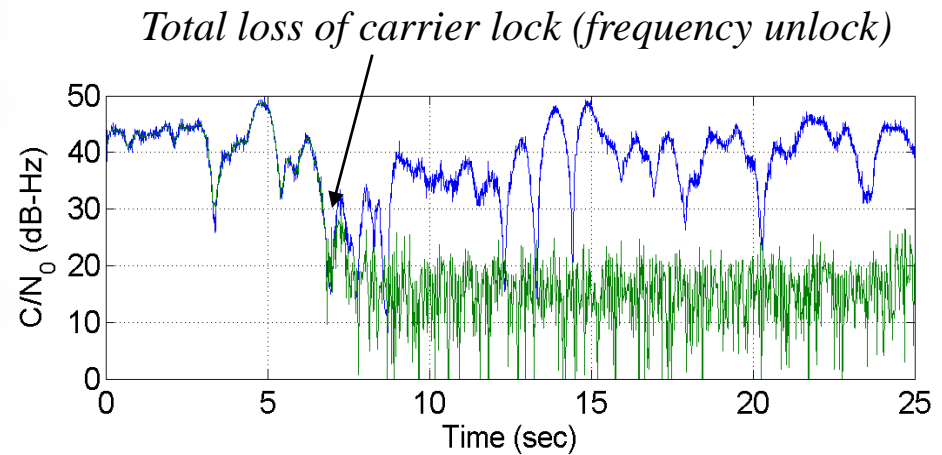
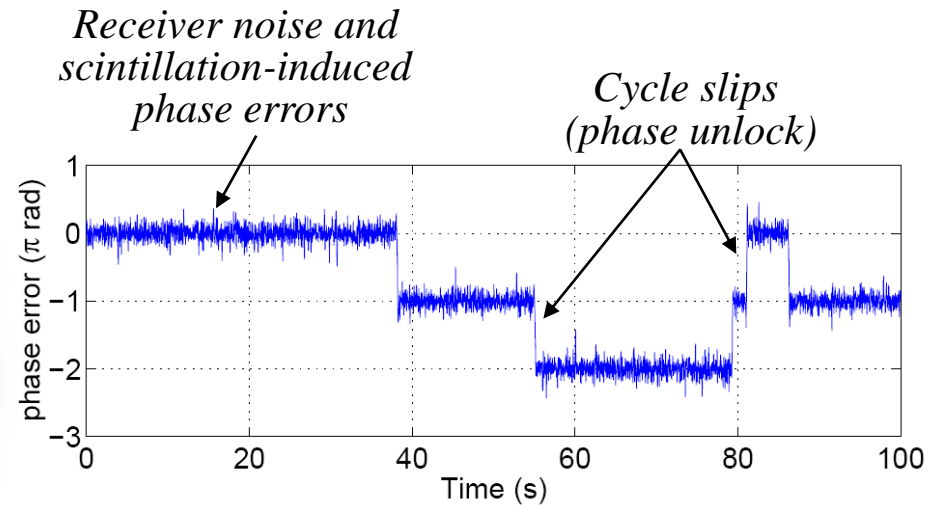
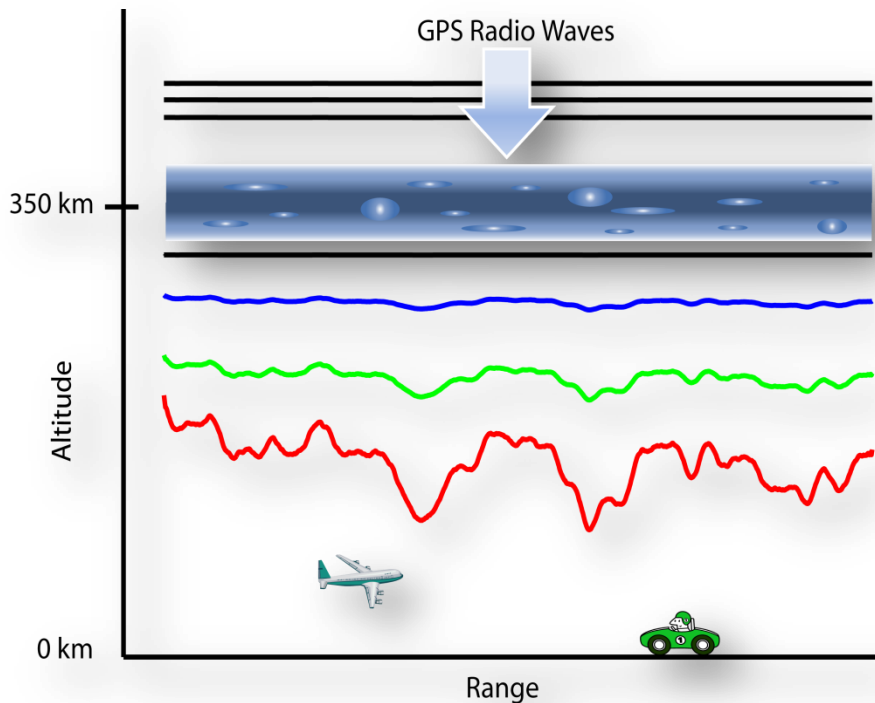


# Civil GPS Spoofing (cont'd)





# Ionospheric Scintillation



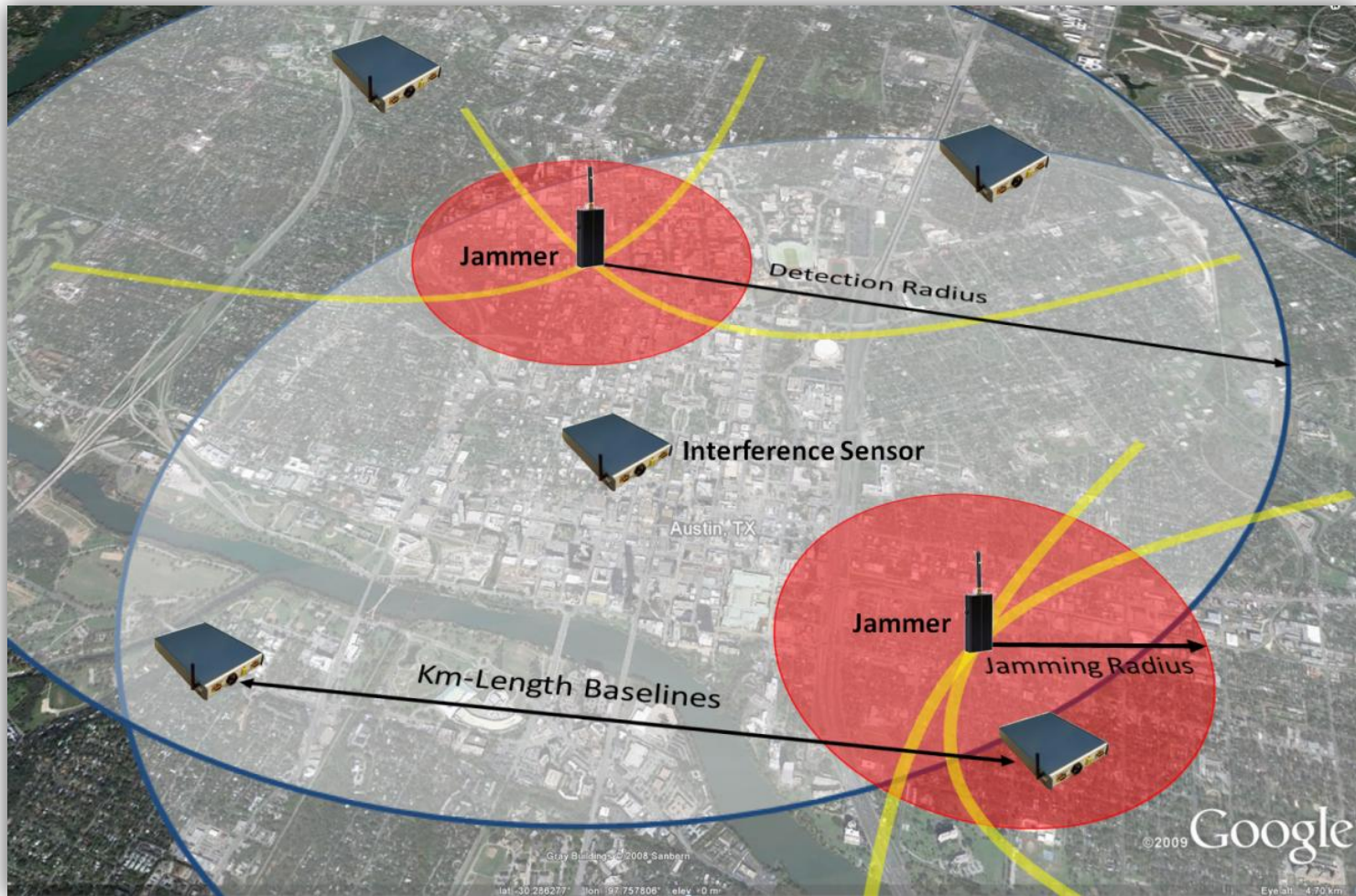


# Research Agenda

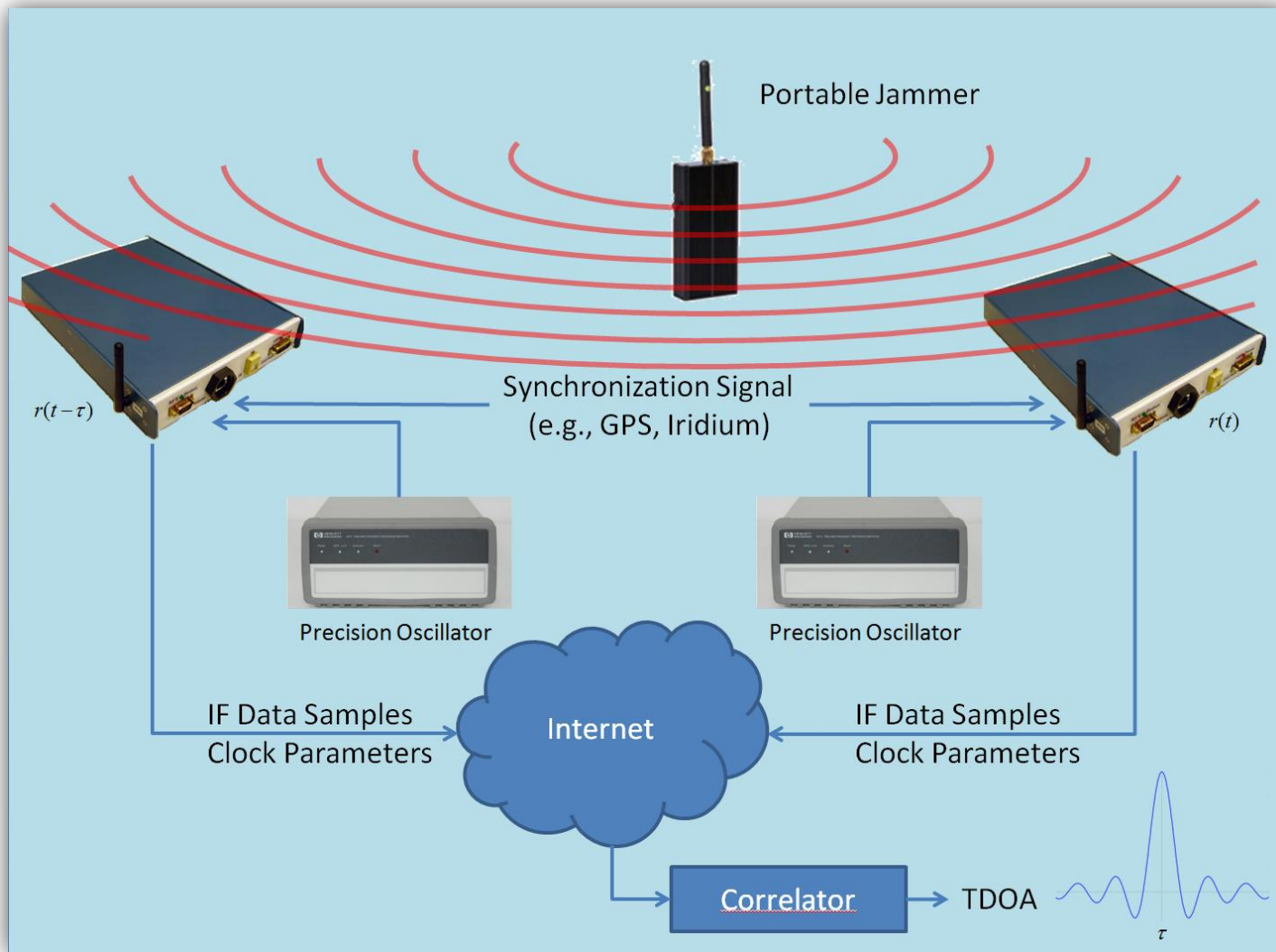
- **GPS Jamming**
  - Develop augmentation-based defenses
  - Locate jamming sources by combining data from a network of receivers
- **GNSS Spoofing**
  - Characterize spoofing signatures
  - Develop receiver-autonomous defenses
  - Develop augmentation-based defenses
- **Natural GNSS Interference**
  - Improve tracking loop robustness to scintillation
- **Network-Centric Navigation**
  - Establish theory for time stability transfer
  - Pursue opportunistic and collaborative navigation

# INTERLOC:

## Network-based Interference Location

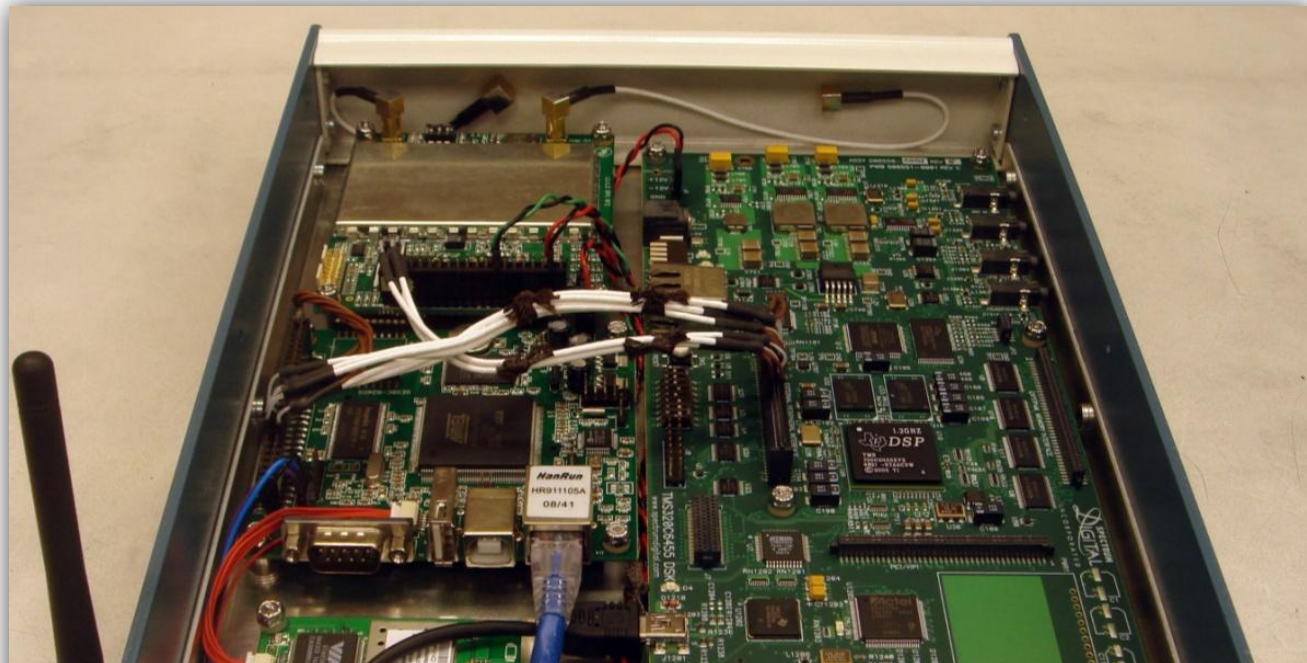


# INTERLOC Functional Diagram





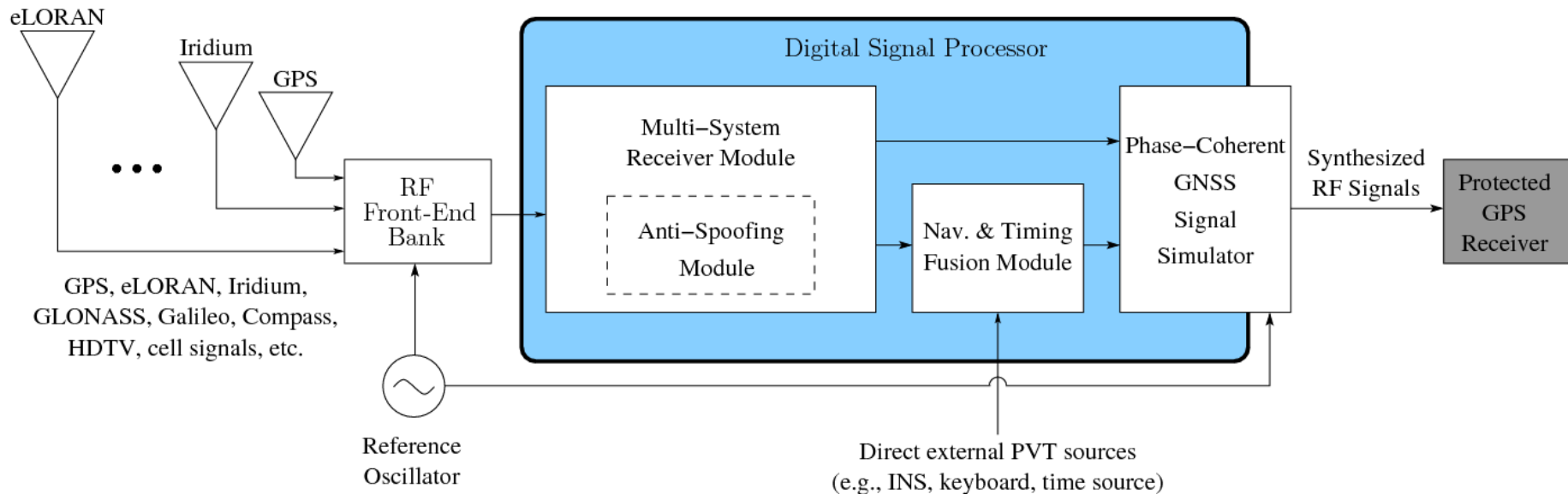
# GRID Software-Defined Radio



*Flexible software-defined radio platform enables:*  
*GPS Assimilator*  
*Spoofing characterization*  
*GPS-based scientific research*  
*Collaborative navigation research*



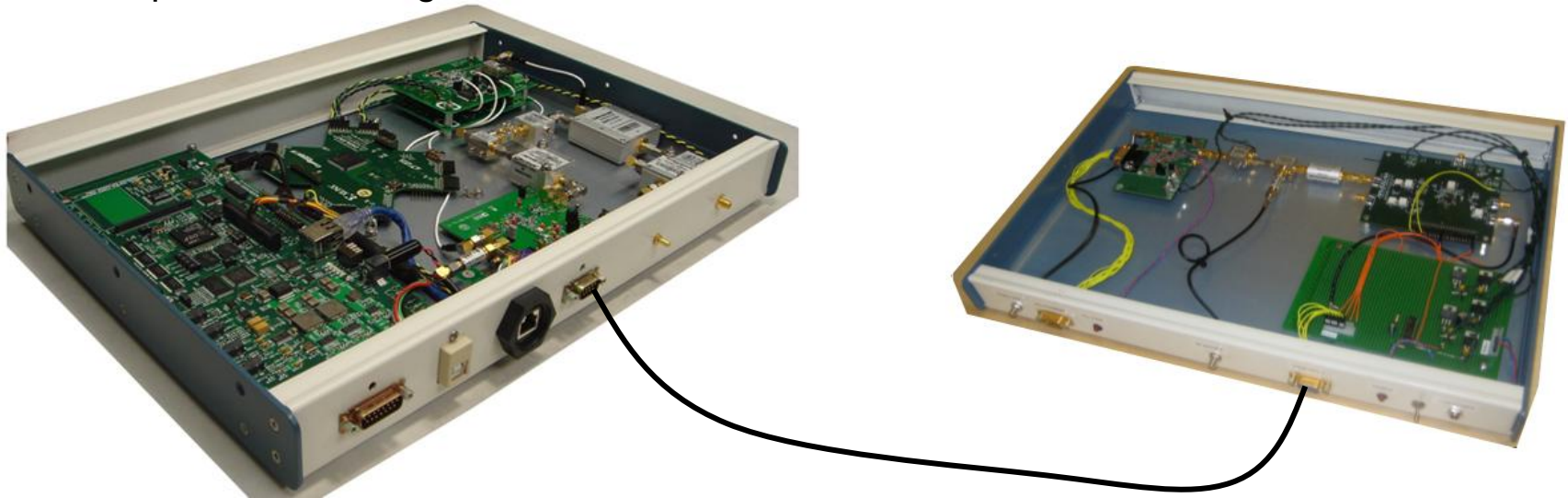
# The GPS Assimilator



*The GPS Assimilator modernizes and makes existing GPS equipment resistant to jamming and spoofing without requiring hardware or software changes to the equipment*

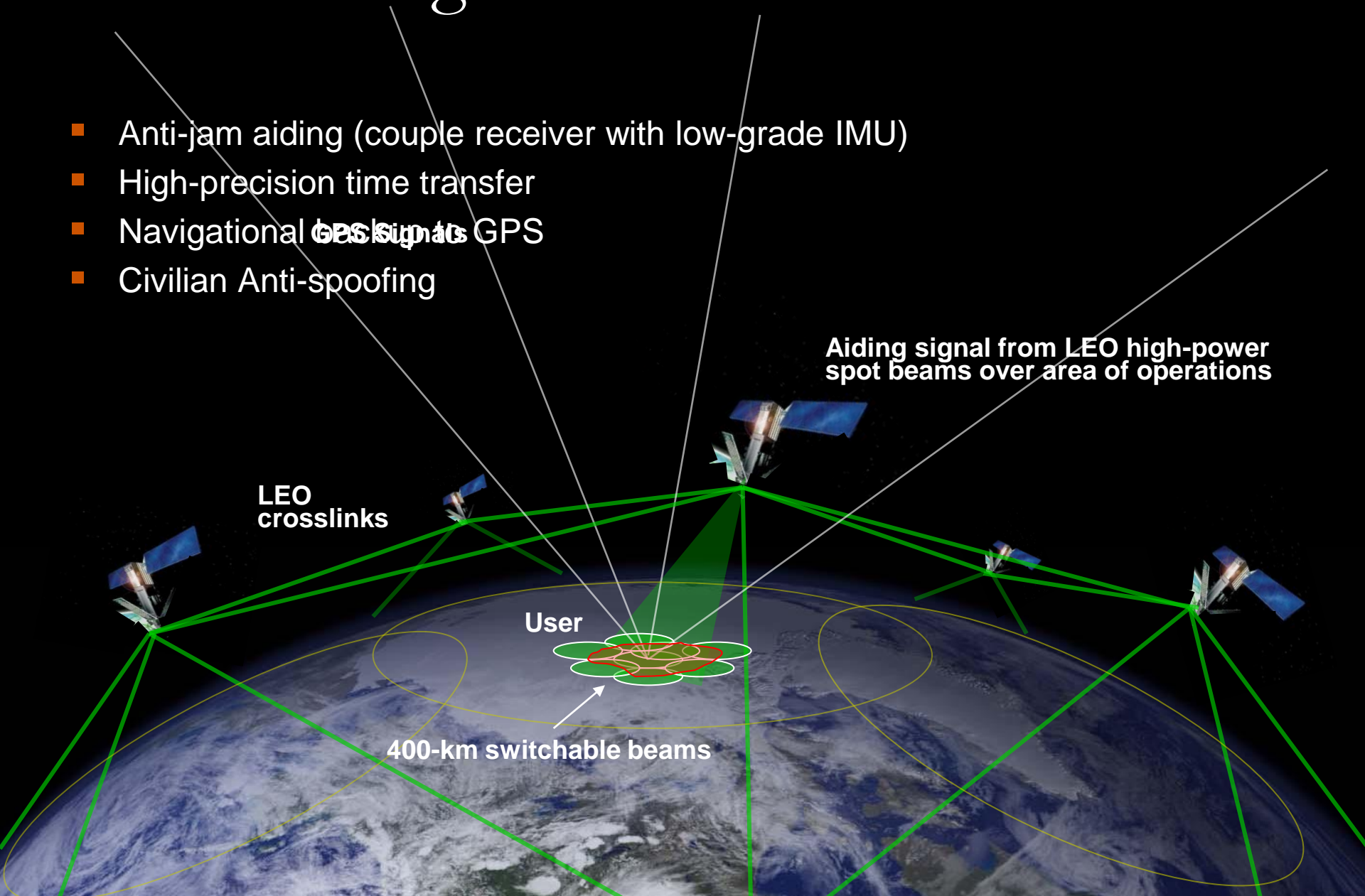
# GPS Assimilator Prototype

- All digital signal processing implemented in C++ on a high-end DSP
- Marginal computational demands:
  - Tracking: ~1.2% of DSP per channel
  - Simulation: ~4% of DSP per channel
- Full capability:
  - 12 L1 C/A & 10 L2C tracking channels
  - 8 L1 C/A simulation channels
  - 1 Hz navigation solution
  - Acquisition in background



# Iridium-Augmented GPS

- Anti-jam aiding (couple receiver with low-grade IMU)
- High-precision time transfer
- Navigational ~~GPS signals~~ GPS
- Civilian Anti-spoofing

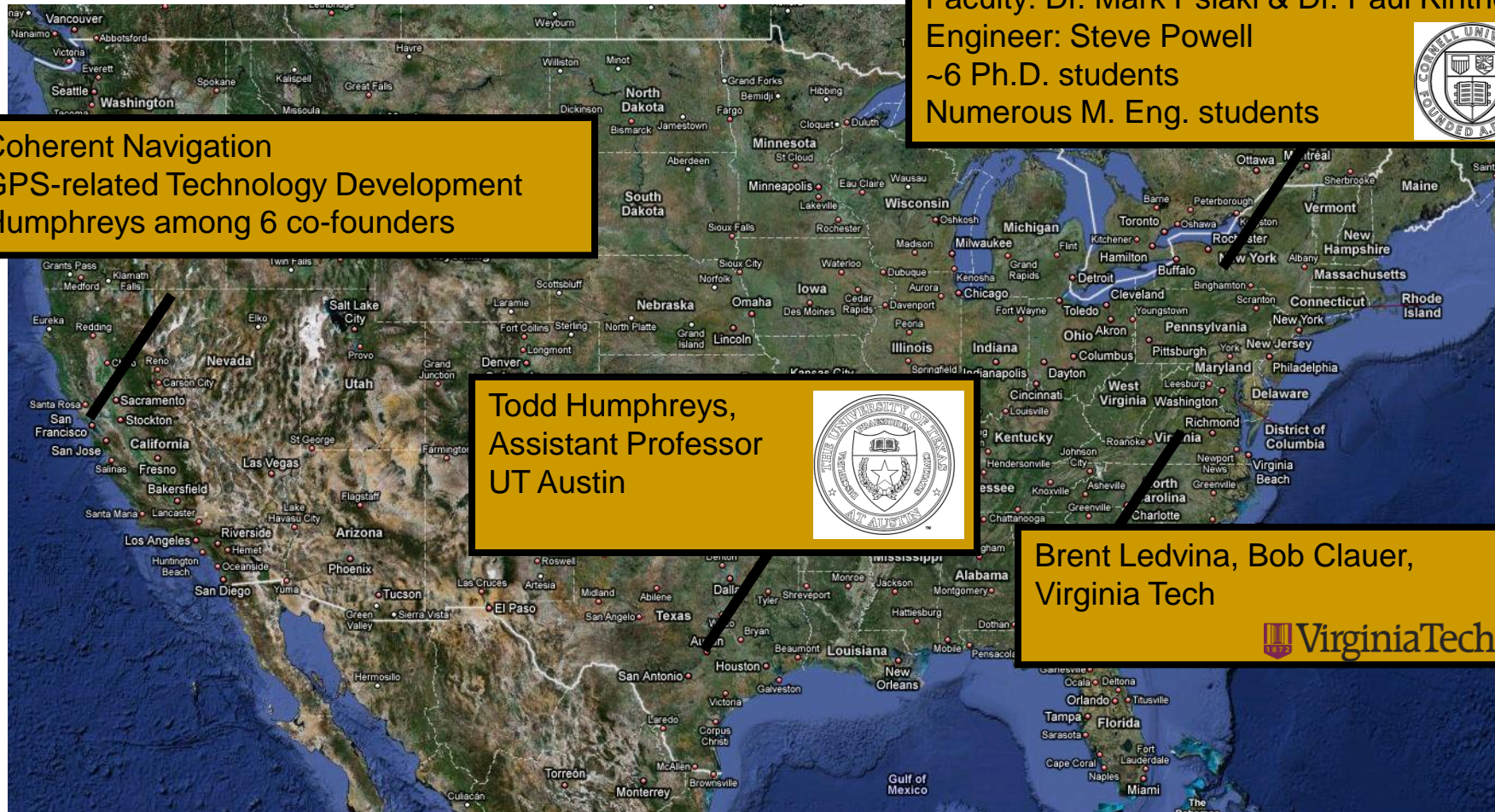


# Radionavigation Lab

- Jahshan Bhatti
  - Ph.D.-track, AE
  - INTERLOC, spoofing defenses
- Muthukumar Pasupathy
  - Ph.D.-track, AE
  - Ionospheric effects on SatNav
- Kyle Wesson
  - Ph.D.-track, ECE
  - Collaborative navigation and time stability transfer
- Ken Pesyna
  - Ph.D.-track, ECE
  - Time stability transfer, cell-phone-based opportunistic navigation
- Zach Tschirhart
  - Undergraduate, AE
  - Lab manager/technician

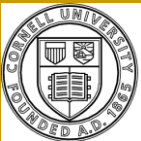


# Outside Collaboration



Coherent Navigation  
GPS-related Technology Development  
Humphreys among 6 co-founders

Cornell GPS Group, Ithaca NY:  
Faculty: Dr. Mark Psiaki & Dr. Paul Kintner  
Engineer: Steve Powell  
~6 Ph.D. students  
Numerous M. Eng. students



Todd Humphreys,  
Assistant Professor  
UT Austin



Brent Ledvina, Bob Clauer,  
Virginia Tech



# Who is Interested in our Work?

- Scintillation-robust software GPS receivers
  - ASTRA (Atmospheric and Space Technology Research Associates LLC)
  - National Science Foundation
- Spoofing characterization and defenses
  - Joint Research Centre, European Commission
  - Office of the Secretary of Defense
  - GPS Wing of the Air Force
- GPS Assimilator
  - DARPA
  - Department of Homeland Security
  - Coherent Navigation